## RESPUESTAS CINEMÁTICA DE LA PARTÍCULA

En las expresiones cinemáticas de velocidades y de aceleraciones el subíndice 1 indica el marco tierra.

Los vectores unitarios  $\{\hat{i},\hat{j}\}$  indicados en las soluciones corresponden a los sentidos horizontal hacia la derecha y vertical hacia arriba respectivamente y además los vectores  $\{\hat{p},\hat{q}\}$  definen otra base ortogonal en el plano.

1.- a) 
$$\overline{V}_1^P = 8\hat{i} + 16\hat{j}$$
 ;  $\overline{a}_1^P = 8\hat{i} + 16\hat{j}$  b)  $y = 2x - 6$  c)  $s(t) = 4\sqrt{5}(2t + t^2)$ 

2.- 
$$\overline{V}_1^P = \frac{8}{3}\pi \hat{i} \quad (m/s)$$
 ;  $\overline{a}_1^P = \frac{8}{3}\pi \hat{i} - \frac{16}{9}\pi^2 \hat{j} \quad (m/s^2)$ 

3.- 
$$\bar{a}_1^A = 2 b v^2 \hat{j} (m/s^2)$$

4.- a) 
$$r = r_o e^{\theta}$$
 ; b)  $\left| \bar{a}_1^P \right| = \frac{2 r_o^2 v_o^2}{r^3}$ 

5.- a) 
$$\left| \overline{a}_{1t}^{P} \right| = \frac{26}{\sqrt{29}}$$
 ; b)  $\rho = \frac{29\sqrt{29}}{\sqrt{165}}$ 

6.- 
$$\left| \overline{V}_{l}^{A} \right| = \sqrt{\frac{2 \left( 2L - d \right) b}{L d}}$$

7.- a) 
$$x^2 + \left(y - \frac{v}{\omega}\right)^2 = \left(\frac{v}{\omega}\right)^2$$
 ; b)  $\rho = \frac{v}{\omega}$  ; c)  $\left|\overline{a}_{1n}^P\right| = \omega v$ 

$$\begin{array}{lll} 8.\text{-} & & \overline{V}_{1}^{P} = -\frac{\pi\,R}{2}\,\,\hat{i} & ; & \overline{a}_{1}^{P} = -\,\frac{\pi\,R}{4}\,\,\hat{i} \,-\,\frac{\pi^{2}\,R}{4}\,\,\hat{j} \\ & & \overline{V}_{2}^{P} = -\frac{\sqrt{2}}{4}\,\pi\,R\,\,\hat{u} & ; & \overline{a}_{2}^{P} = -\frac{\pi\,R\,\,\sqrt{2}}{16}\,\,(\,\,2+\pi\,\,)\,\,\hat{u} \\ & & \text{donde 2 es la barra} \end{array}$$

9.- 
$$\overline{V}_{i}^{P} = -\sqrt{2} v \hat{i}$$
 ;  $\overline{a}_{1}^{P} = \frac{1}{R} v^{2} \hat{i} + \frac{2}{R} v^{2} \hat{j}$ 

10.- 
$$\bar{a}_1^P = \frac{v^2}{(1+x^2)^2} (-x \hat{i} + \hat{j})$$

$$11. \quad \overline{V}_{l}^{P} \, = \, -\frac{1}{2} \, v \, \, \hat{i} \, - \, v \, \, \hat{j} \quad (m/s) \qquad ; \qquad \overline{a}_{l}^{P} \, = \, -\frac{1}{20} \, v^{2} \, \, \hat{i} \quad (m/s^{2})$$

$$\overline{V}_2^P \; = \; -\frac{1}{2} \; v \; \; \hat{i} \quad (\text{m/s}) \qquad ; \qquad \qquad \overline{a}_2^P \; = \; -\frac{1}{20} \; v^2 \; \; \hat{i} \quad (\text{m/s}^2) \label{eq:V2P}$$

donde 2 es la pieza

12.- 
$$\overline{V}_2^P = -\frac{\sqrt{2}}{2} v \hat{p}$$
 ;  $\overline{a}_2^P = \frac{\sqrt{2}}{4 b} v^2 \hat{p}$  donde 2 es la barra

13.- 
$$\overline{V}_{l}^{A} = \sqrt{2} v \hat{i}$$
 ;  $\overline{a}_{l}^{A} = \frac{1}{b} v^{2} \hat{i}$ 

14.- 
$$\overline{V}_{1}^{P} = \sqrt{2\pi b} R (\sqrt{2} - 1) \hat{i}$$
  
 $\overline{a}_{1}^{P} = 2Rb \hat{i} - 2(3 - 2\sqrt{2})\pi b R \hat{j}$ 

15.- 
$$\left| \overline{a}_{1t}^{P} \right| = 0$$

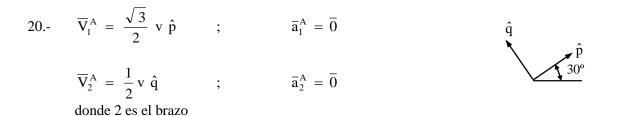
16.- 
$$s = b \omega t$$

17.- a) 
$$\bar{a}_1^P = -\sqrt[3]{\frac{Lb^2}{3}} \hat{j}$$
; b)  $\bar{a}_1^P = \left[\frac{Lb^2}{6}(3+\pi)\right]^{\frac{1}{3}} \hat{i} + \frac{b^2}{288L} \left[\frac{36L}{b}(3+\pi)\right]^{\frac{4}{3}} \hat{j}$ 

18.- 
$$\overline{V}_{1}^{C2} = -\sqrt{2} \, v \, \hat{i}$$
 ;  $\overline{a}_{1}^{C2} = -\frac{1}{R} \, v^{2} \, \hat{i} + \frac{2}{R} \, v^{2} \, \hat{j}$ 

donde 2 es la barra

19.- 
$$\overline{V}_{1}^{P} = \frac{3}{4}\pi R \hat{p}$$
 ;  $\overline{a}_{1}^{P} = \frac{1}{2}\pi R \hat{p} + \frac{9}{16}\pi^{2} R \hat{q}$   $\overline{V}_{2}^{P} = -\frac{3\sqrt{2}\pi R}{8} \hat{j}$  ;  $\overline{a}_{2}^{P} = -\frac{\sqrt{2}\pi R}{32} (8 + 9\pi) \hat{j}$   $\hat{q}$   $\hat{p}$  donde 2 es la pieza



21.- a) 
$$y = h - \frac{g}{2} \sqrt[3]{\left(\frac{3x}{\omega g \cos \lambda}\right)^2}$$
 ; b)  $\delta = \frac{2\omega h \cos \lambda}{3} \sqrt{\frac{2h}{g}}$ 

22.- 
$$\overline{V}_1^P = \sqrt{3} R \omega \hat{j}$$
 ;

$$22. - \overline{V}_{l}^{P} = \sqrt{3} \, R \, \, \omega \, \, \hat{j} \qquad ; \qquad \qquad \overline{a}_{l}^{P} = \, 3 \, R \, \, \omega^{2} \, \, \hat{i} \, \, - \, \frac{R}{2} \omega^{2} \, \, \hat{j}$$

23.- 
$$\overline{V}_1^A = \sqrt{2} v \hat{i}$$

$$23. - \quad \overline{V}_{l}^{A} \, = \sqrt{2} \, v \, \, \hat{i} \qquad \qquad ; \qquad \qquad \overline{a}_{l}^{A} \, = -\frac{1}{R} \, v^{2} \, \, \hat{i} \, - \frac{2}{R} \, v^{2} \, \, \hat{j}$$

24.- 
$$\overline{V}_1^C = \overline{0}$$

; 
$$\overline{a}_1^C = 2\omega^2 L \hat{j}$$

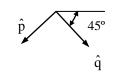
25.- 
$$r(t) = \frac{\sqrt{2}}{2} \left[ vt + \sqrt{2} r_o \right]$$
 ;  $\theta(t) = Ln \left[ \frac{\sqrt{2} v}{2r} t + 1 \right]$ 

$$\theta(t) = \operatorname{Ln} \left[ \frac{\sqrt{2} \, \mathrm{v}}{2 \, \mathrm{r_0}} t + 1 \right]$$

$$26.- \qquad \overline{a}_{1}^{A} \, = \, -\frac{b^{4}}{a^{2}\,y^{3}}\,v^{2}\,\,\,\hat{j}$$

$$27.- \overline{V}_1^A = \frac{\pi R}{4} \hat{p}$$

$$27.- \quad \overline{V}_{l}^{A} \, = \frac{\pi \, R}{4} \, \, \hat{p} \qquad \qquad ; \qquad \qquad \overline{a}_{l}^{A} \, = \frac{\pi \, R}{8} \, \, \hat{p} \, + \frac{\pi^{2} \, R}{16} \, \, \hat{q}$$



$$\bar{a}_1^A = \bar{0}$$

$$\overline{V}_2^A = v$$

$$\bar{a}_{2}^{A} = \bar{0}$$

29.- a) 
$$x^2 + y^2 = \left(\frac{L}{2}\right)^2$$
; b)  $\overline{V}_1^{C2} = \frac{1}{2} v \hat{i} - \frac{1}{2} v \hat{j}$ 

b) 
$$\overline{V}_{1}^{C2} = \frac{1}{2} v \hat{i} - \frac{1}{2} v \hat{j}$$

donde 2 es la barra y C su punto medio

$$30.- R = 12 (m)$$

31.- 
$$s = 8b$$

32.- a) 
$$\overline{V}_{1}^{A} = \frac{v\sqrt{1+4x^{2}}}{(1+8x^{2})}(\hat{i}+4x\hat{j})$$
 ; b)  $\dot{\phi} = \frac{2v}{(1+8x^{2})\sqrt{1+4x^{2}}}$  ; c)  $\overline{a}_{2}^{A} = \overline{0}$ 

b) 
$$\dot{\phi} = \frac{2 \, v}{(1 + 8 \, x^2) \, \sqrt{1 + 4 \, x^2}}$$
;

c) 
$$\bar{a}_2^A = \bar{0}$$

donde 2 es la varilla OB

$$33.- \qquad t = \frac{\pi}{2} \sqrt{\frac{R}{a}}$$

34.- a) 
$$\overline{V_1}^B = \frac{2\sqrt{3}}{3} v \hat{p}$$
  $\frac{\hat{p}}{60^\circ}$  b)  $\dot{\theta} = \frac{2\sqrt{3}}{31} v$ 

b) 
$$\dot{\theta} = \frac{2\sqrt{3}}{3L}v$$

35.- 
$$\dot{\theta} = -\frac{4\sqrt{3}}{9}$$
 (rad/s) ;  $\ddot{\theta} = -\frac{64\sqrt{3}}{81}$  (rad/s<sup>2</sup>)

$$\ddot{\theta} = -\frac{64\sqrt{3}}{81} \text{ (rad/s}^2)$$

36.- 
$$\left| \overline{V}_{l}^{P} \right| = \sqrt{240}$$
 (cm/s)